



140,000 Hz COPLANAR APPARENT RESISTIVITY OF THE ALASKA HIGHWAY CORRIDOR, EAST-CENTRAL ALASKA

PARTS OF NABESNA and TANACROSS QUADRANGLES

by
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RESISTIVITY

The RESOLVE EM system measured inphase and quadrature complex signals using a vertical loop with two coplanar coil-pair operated at 3300 Hz while five horizontal capacitive sensors were active at 100, 200, 400, 2000, 40,000 and 140,000 Hz. EM data were sampled at 0.1 second intervals. The EM system responds to bedrock conductors, surface conductivity, and man-made signal sources. Apparent resistivity is generated from the inphase and quadrature signals using a model for 140,000 Hz using the pseudo-layer half-space model. The data were interpolated onto a regular 80 m grid using a modified Akima (1970) technique.

Akima, H., 1970, A new method of curve fitting based on local procedures, *Journal of the Association of Computing Machinery*, v. 17, no. 4, p.509-522.

RESISTIVITY ALTITUDE LIMITS

In areas where the EM bird height exceeded 100 m, and the inphase and quadrature signals were below 3 pT, the apparent resistivity value for that cell was blank. This avoids meaningless resistivity calculations due to small signals in areas where the helicopter flew higher to avoid cultural objects or for safety reasons.

SURVEY HISTORY

This map has been compiled and drawn under contract between the State of Alaska, Department of Natural Resources, Division of Geological & Geophysical Surveys (DGGGS) and Stevens Exploration Management Corp. Airborne geophysical data for the new area were acquired and processed by Fugro Airborne Surveys Corp. in 2006 and early 2007. This map and other products from this survey are available by mail order or in person from DGGGS, College of Earth, Geoenvironmental and Planetary Sciences, University of Alaska Fairbanks, P.O. Box 755000. Published maps are also available for viewing or download as Adobe Acrobat Files (*.pdf) on our Web site (<http://www.dggs.dnr.state.ak.us/pubs/>).

DESCRIPTIVE NOTES

The geophysical data were acquired with a RESOLVE Electromagnetic (EM) system and a Soltrex cesium magnetometer. The EM and magnetic sensors were flown at a height of 100 feet. In addition the survey recorded data with a Global Positioning System navigation system, 50/60 Hz monitors and video cameras. The survey was conducted using AS350B-2 and AS350B-3 Squirrel helicopters at a mean terrain clearance of 200 feet above North Sea level (N.S.L.) and a flight altitude with a spacing of a quarter of a mile. Tie lines were flown every 10 miles. The flight lines are at intervals of approximately 3 miles.

An Ashtech G22 NAVSTAR / GLONASS Global Positioning System was used for navigation. The helicopter attitude was determined by GPS and IMU using post-flight differential positioning to a relative accuracy of better than 5 m. Flight path position was projected onto the ground using UTM zone 7 spheroid, 1927 North American datum using a mean ellipsoid semi-major axis length constant of 0 and an east constant of 500,000. Positional accuracy of the presented data is better than 10 m. with respect to the UTM grid.

